



Le défi de l'intégration des ressources renouvelables distribuées dans les réseaux électriques

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23 octobre, 2014**

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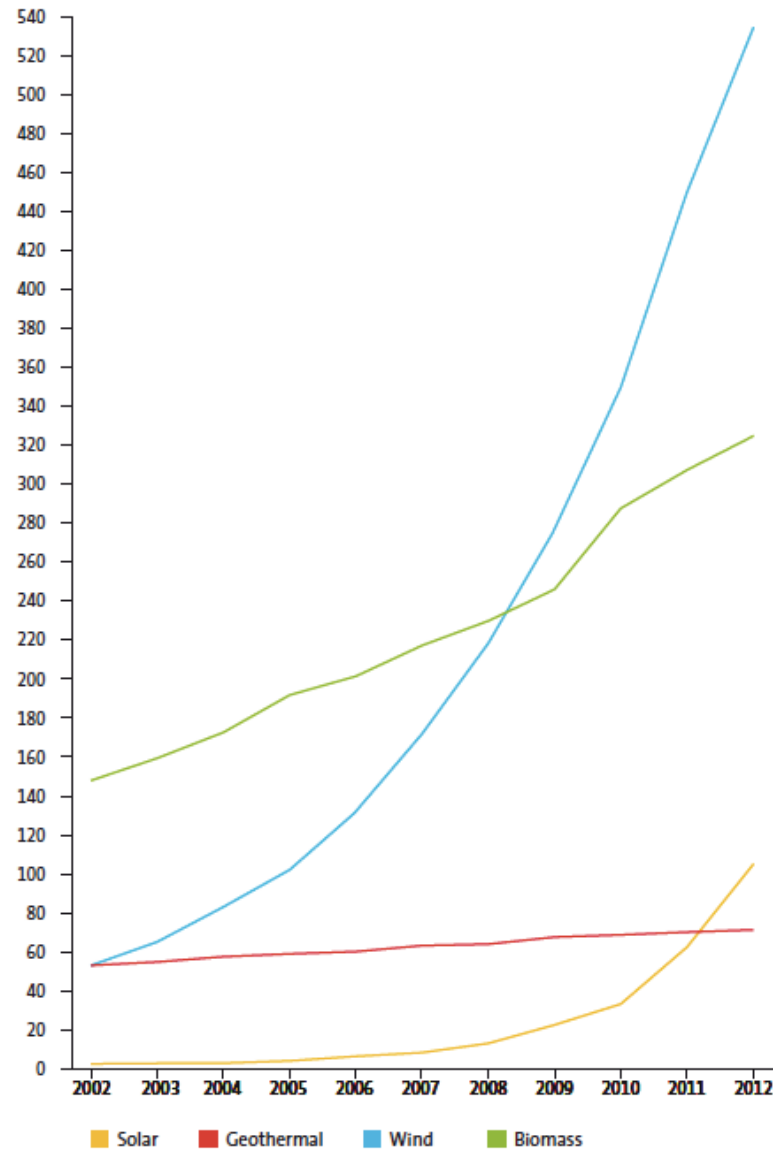
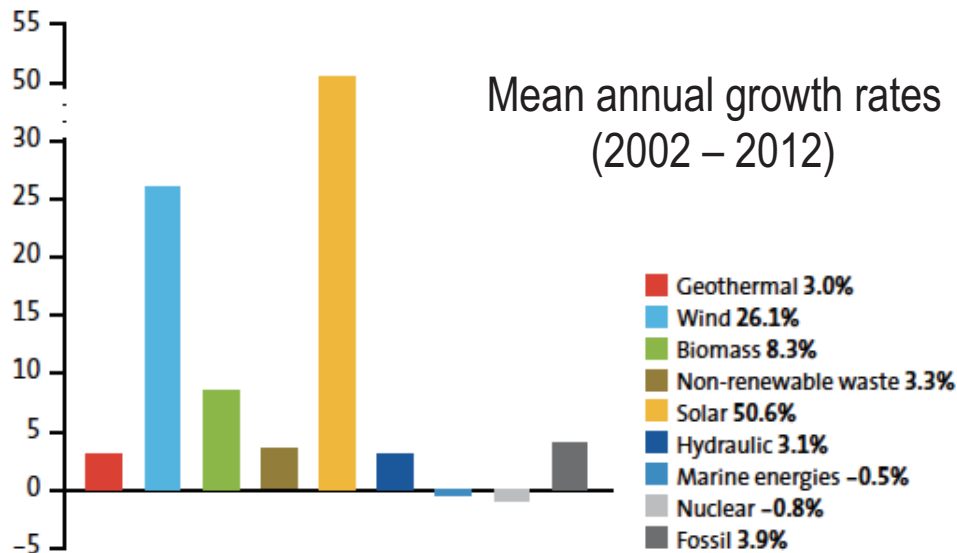
Outline

The Drivers



The Drivers

The worldwide response in terms of **increase of renewables for the production of electricity**

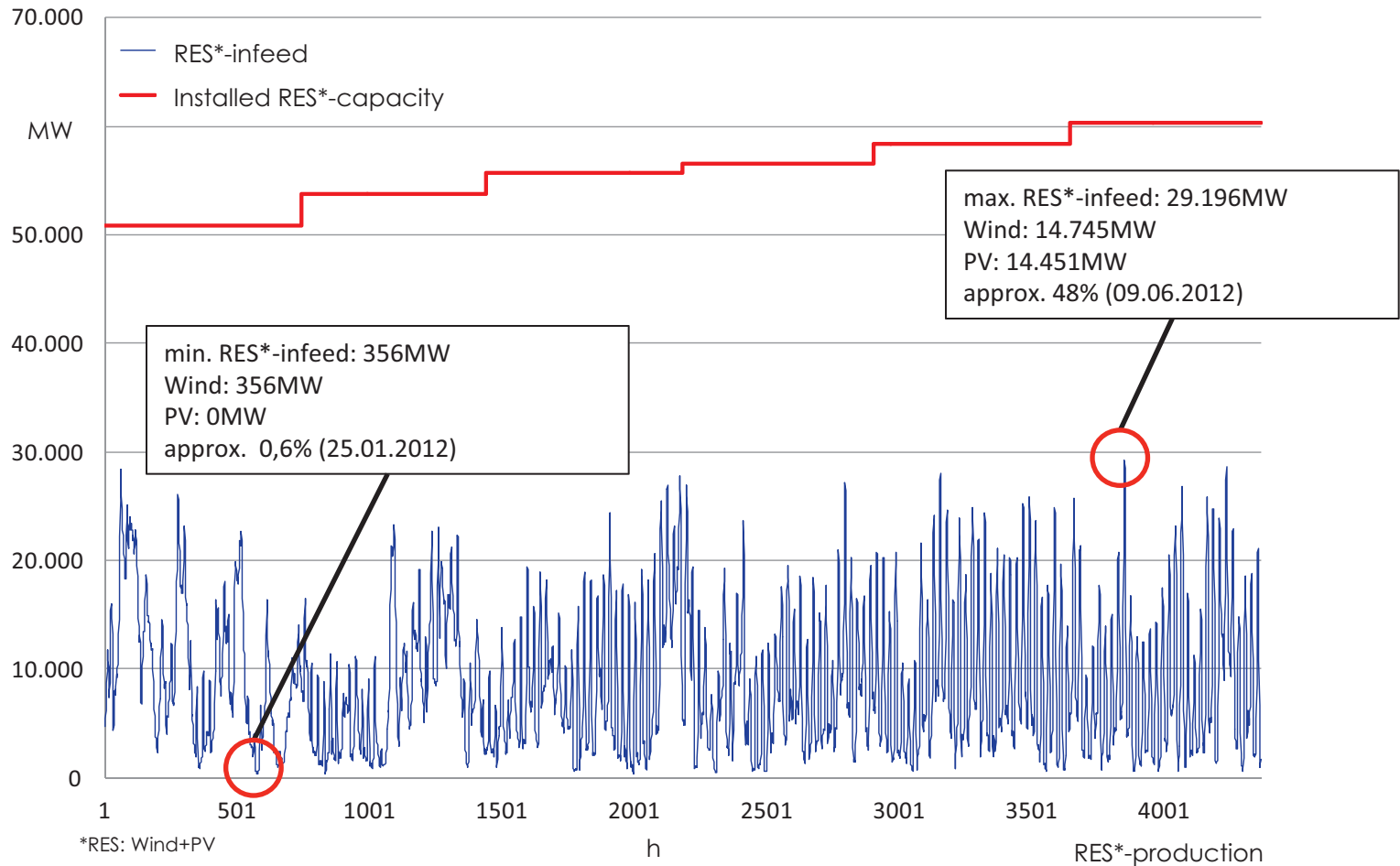


Source: 15th inventory of worldwide electricity production from renewable energy resources. 2013.

The Drivers

Seasonal volatility (Wind+PV)

Installed capacity vs real infeed: the case of Germany

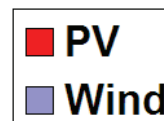
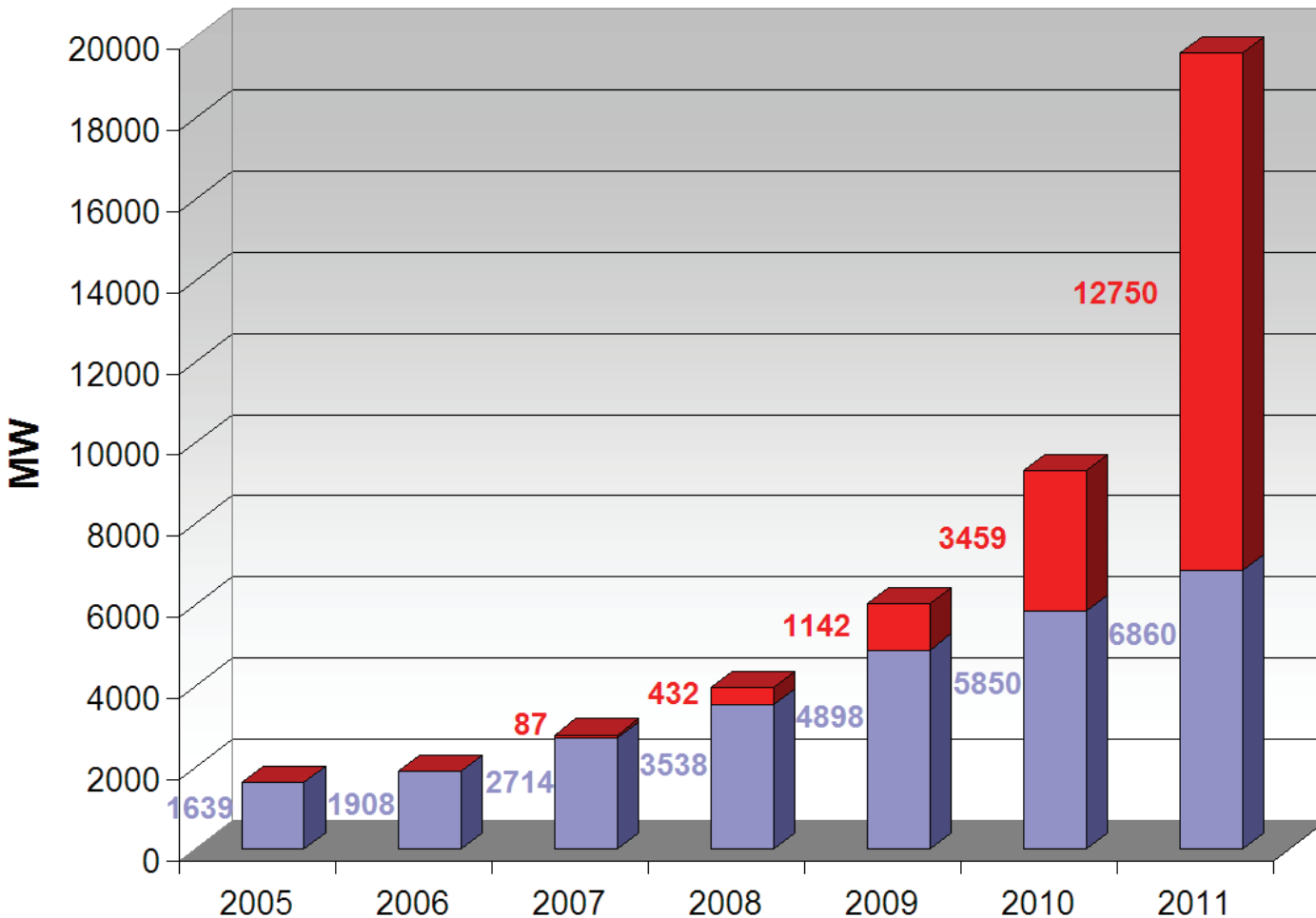


The Drivers

Grow rate of decentralized energy resources: the case of Italy

In April 2013, the PV installed capacity has reached **16.5 GWp**

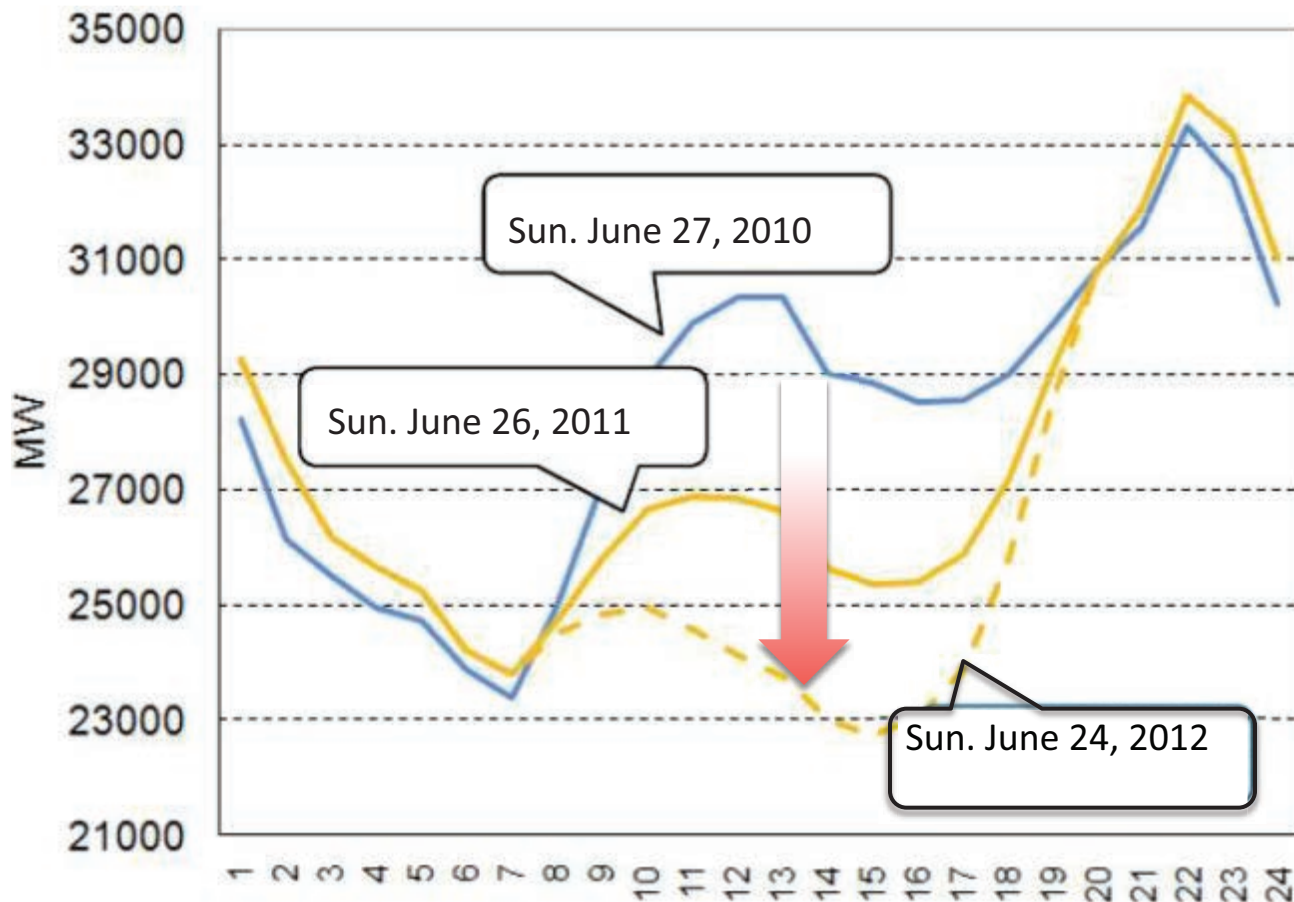
Energy prod:
2011: 10.7 TWh
2012: 18.8 TWh
½ 2013: 13.8 TWh (7.3% of the demand)



The Drivers

Impact on the daily load curve: the case of Italy

Remark#1: possibility to have phases along the day with large reduction of the net power flow on the transmission network.

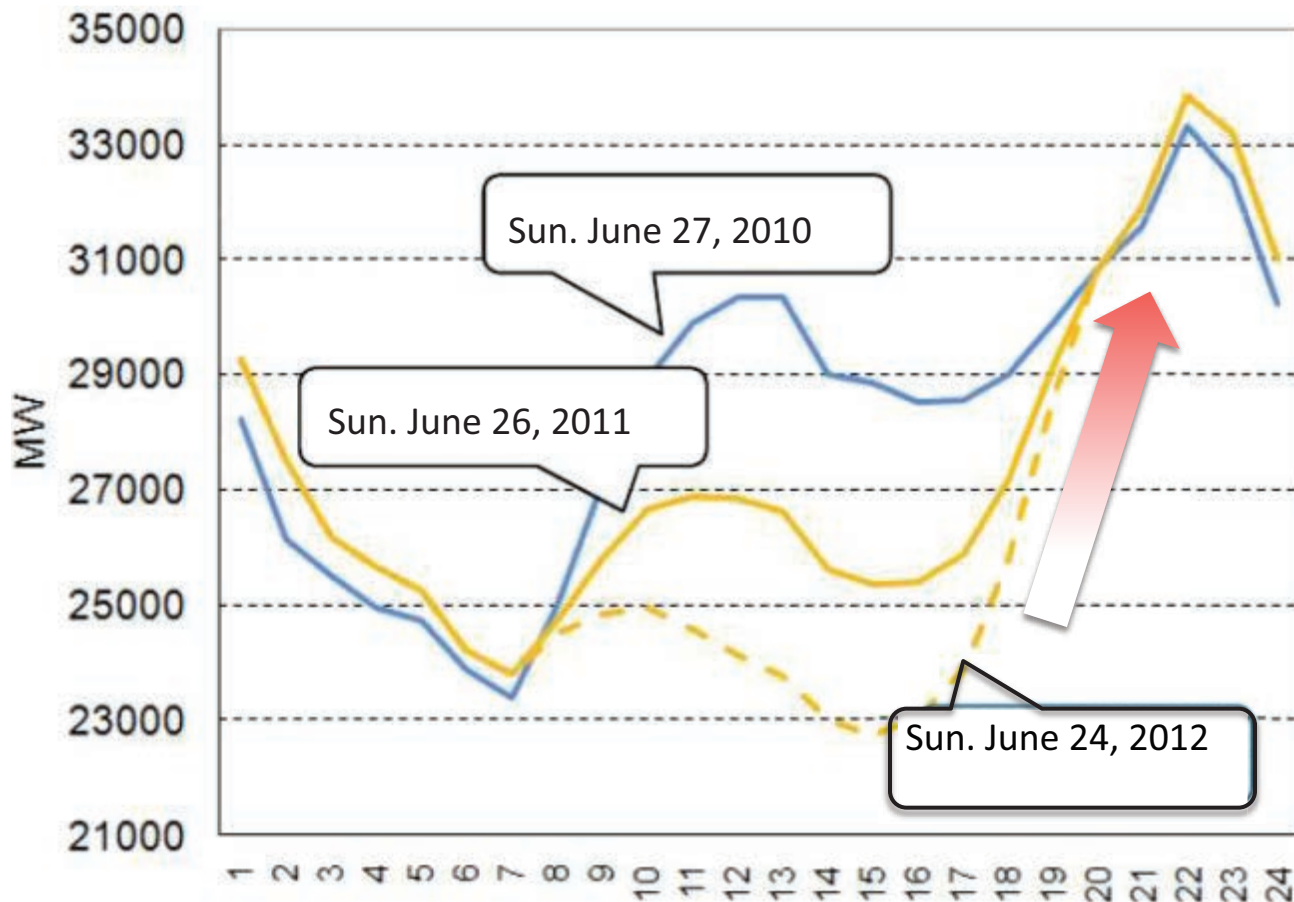


Source: Terna S.p.A.

The Drivers

Impact on the daily load curve: the case of Italy

Remark#2: need of
faster ramping in the
evening hours

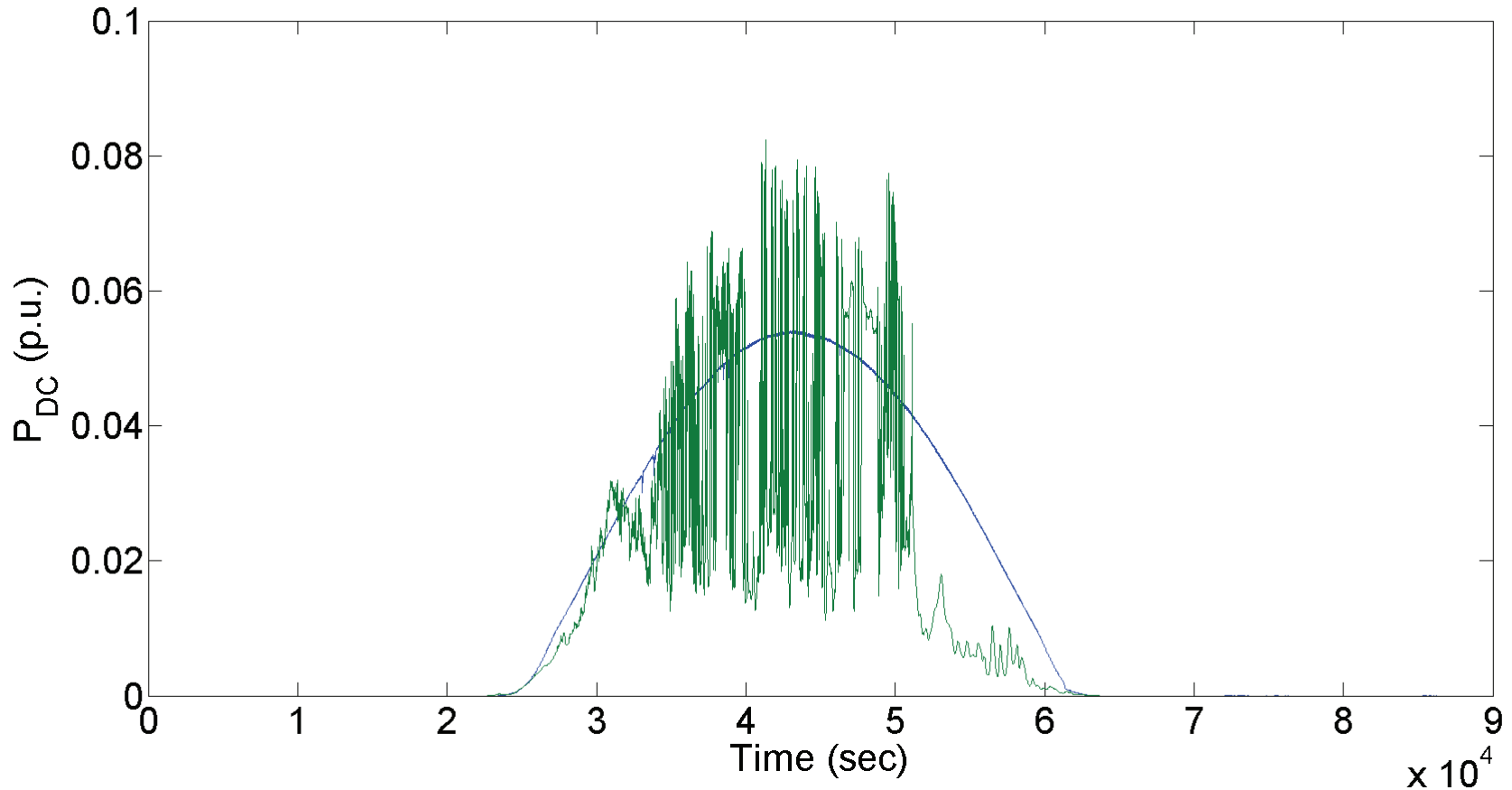


Source: Terna S.p.A.

The Drivers

Short-term volatility (PV)

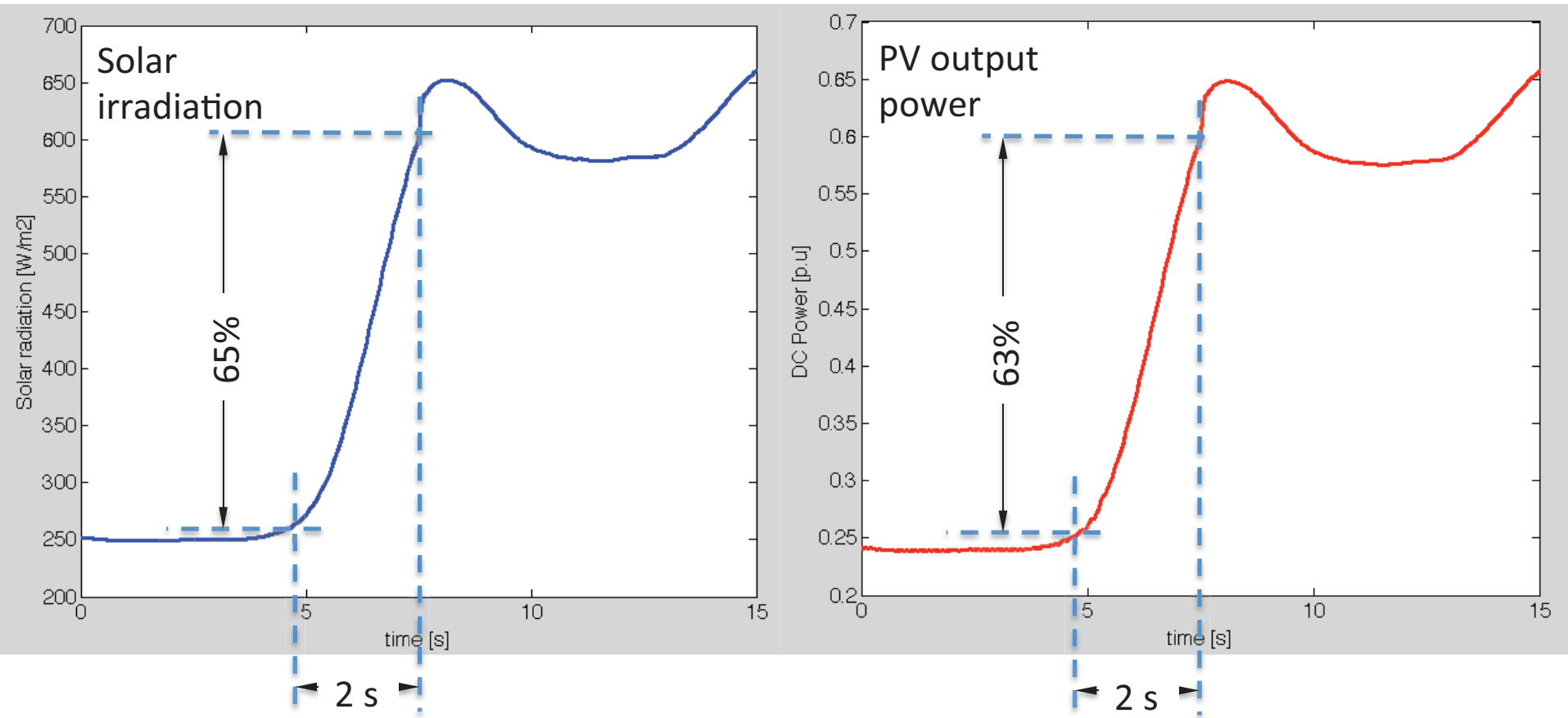
Example of daily measured power injected by solar arrays at EPFL



The Drivers

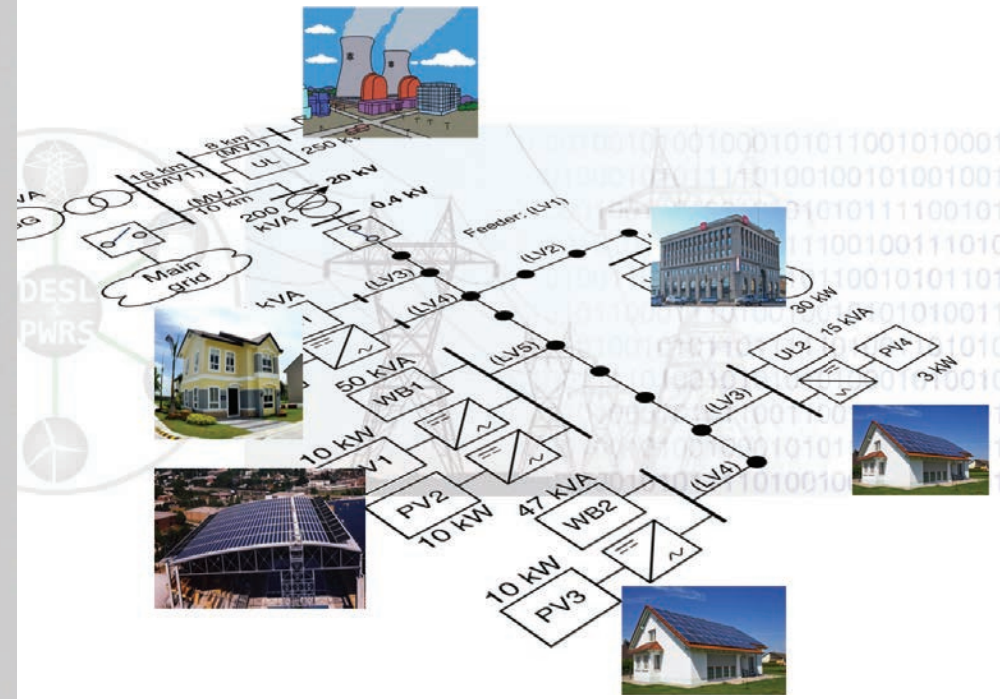
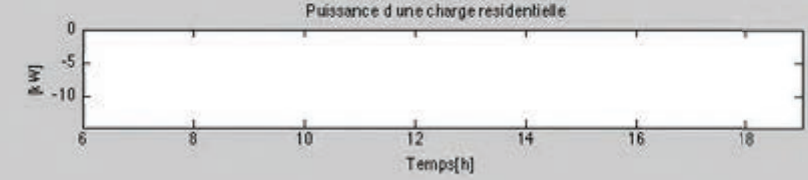
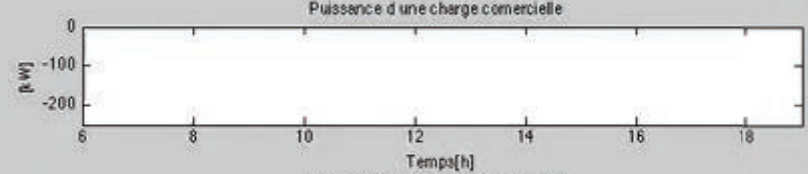
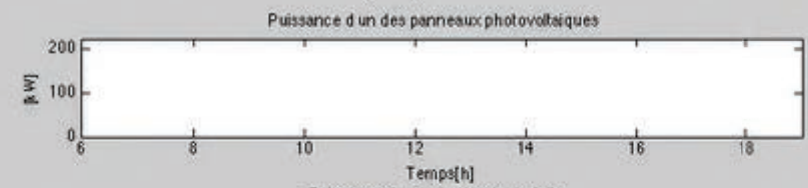
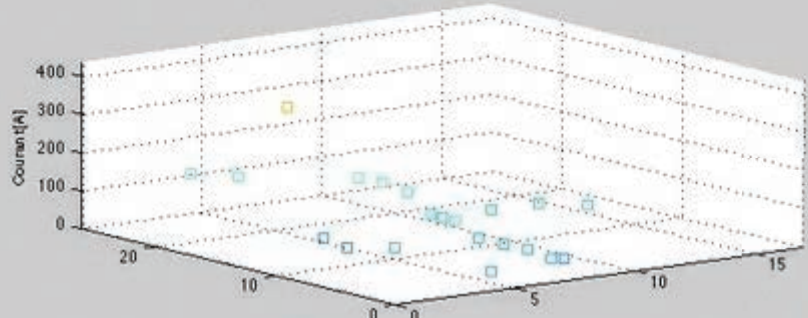
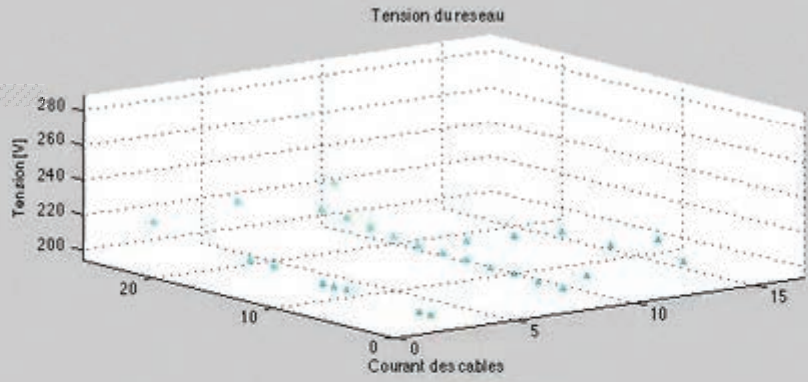
Short-term volatility (PV)

Example of daily measured power injected by solar arrays at EPFL



Impact of renewables short-term volatility on the quality of service of the grid

- Voltage and line capacity
- Volatility = difficult control (optimal)



Outline



The Challenges

The Challenges

Challenges for grids

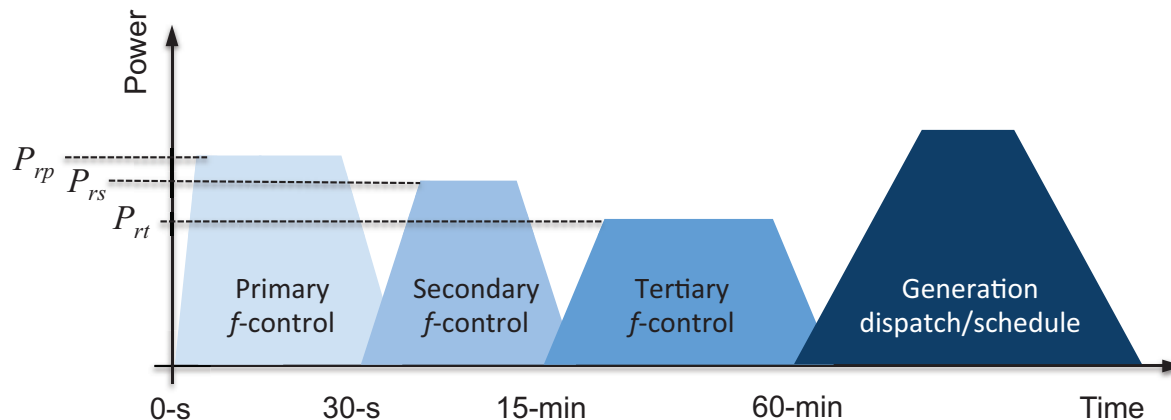
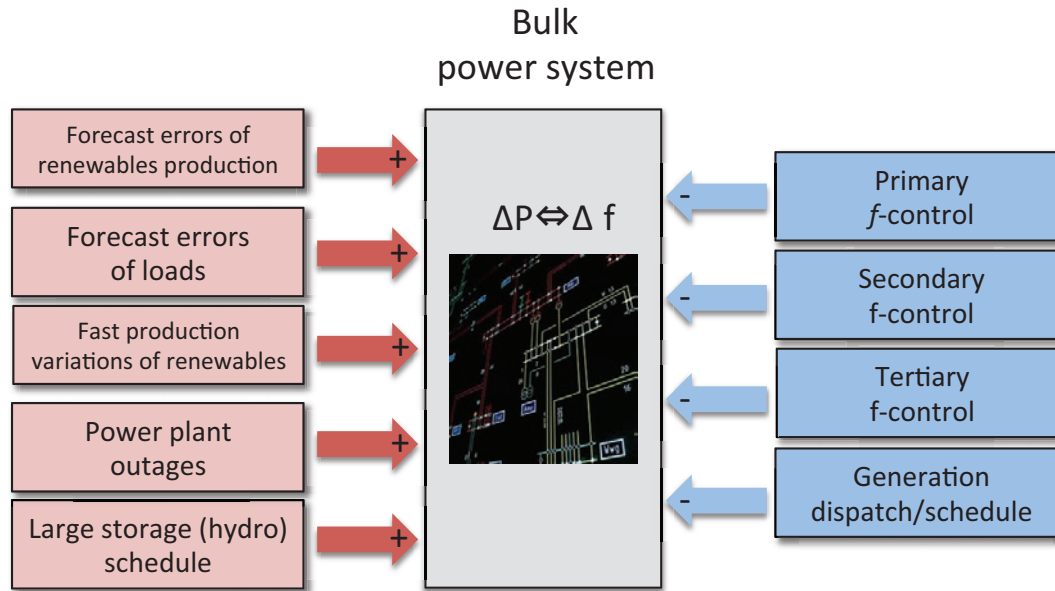
- quality of service in distribution networks;
- participation of distributed generation to frequency and voltage support (*Virtual Power Plant*)
- autonomous small scale grids with little inertia

Solutions

- fast ramping generation (fossil fuel based)
- local storage, demand response
- *real time control* of local grids

The Challenges

Optimal and robust control of bulk systems with high-volatile resources



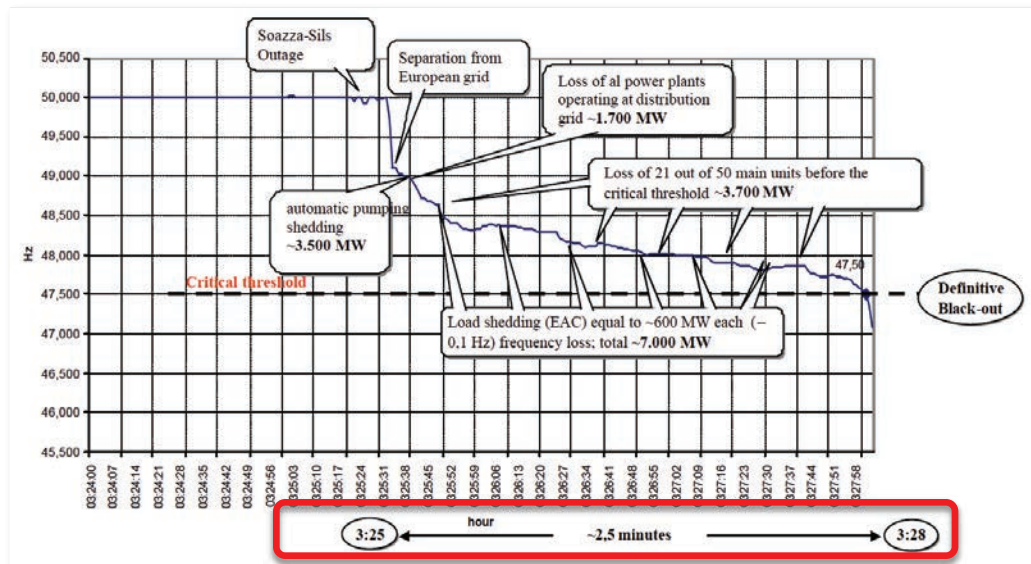
Main challenges:
can we still use
this approach to
control systems
with major
penetration of
stochastic
resources ?

The Challenges

Towards inertia-less systems ?

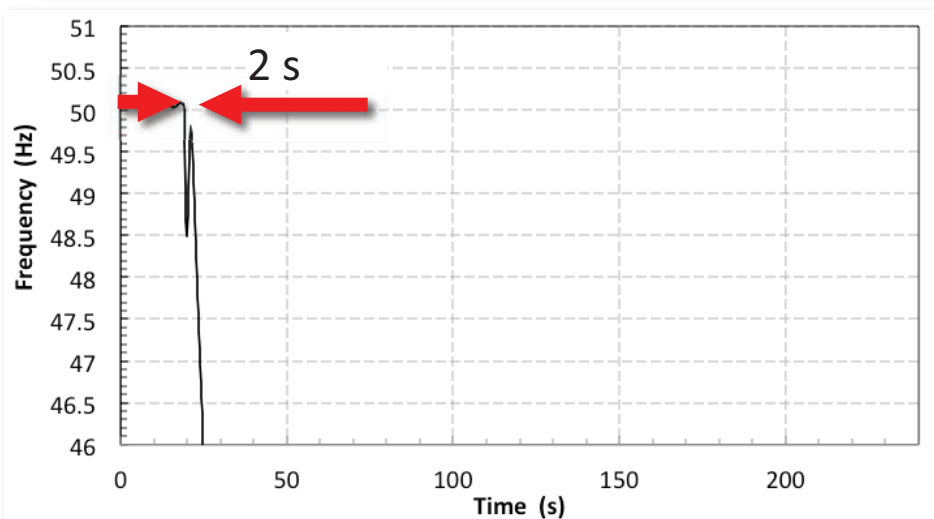
2003 blackout in Italy frequency trend

Source: UCTE Interim Report of the Investigation Committee on the 28 September 2003 Blackout in Italy



2009 blackout during the islanding maneuver of an active distribution network

Source: A. Borghetti, C. A. Nucci, M. Paolone, G. Ciappi, A. Solari, "Synchronized Phasors Monitoring During the Islanding Maneuver of an Active Distribution Network", IEEE Trans. On Smart Grid, vol. 2, issue: 1, march, 2011, pp: 70 – 79.



The Challenges

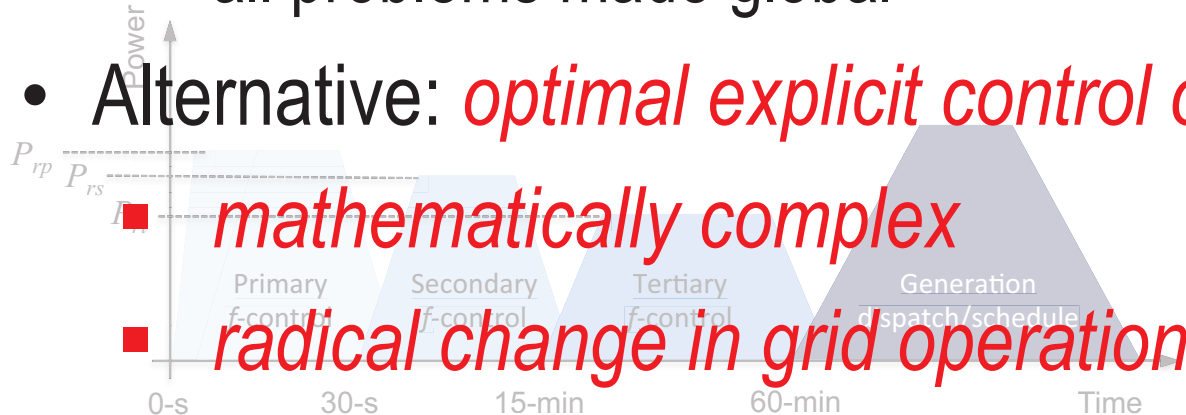
Optimal and robust control of bulk systems with high-volatile resources

- Typically done with droop controllers on main power plants

- Problems:

- system does not know the state of resources (e.g. temperature in a building, state of charge in a battery)
 - all problems made global

- Alternative: *optimal explicit control of power setpoints*



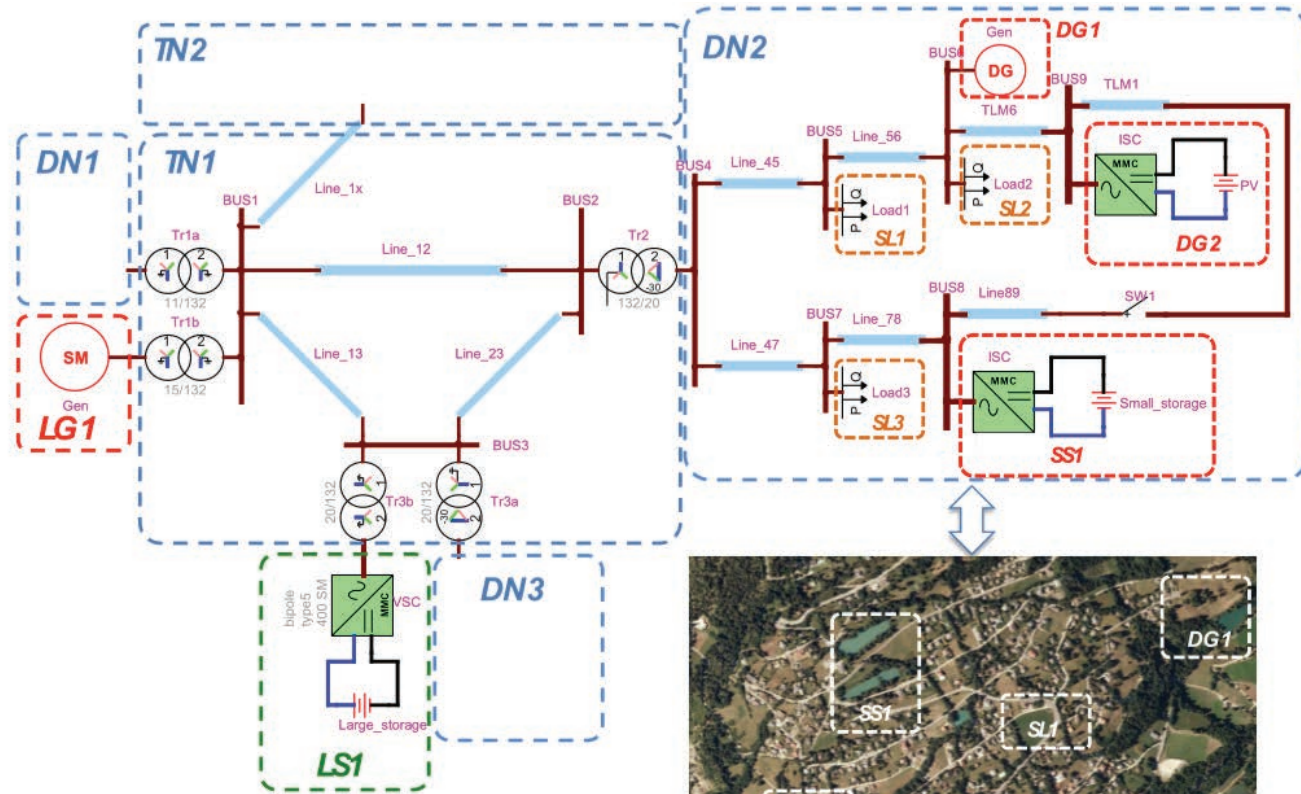
The COMMELEC Protocol



The COMMELEC idea

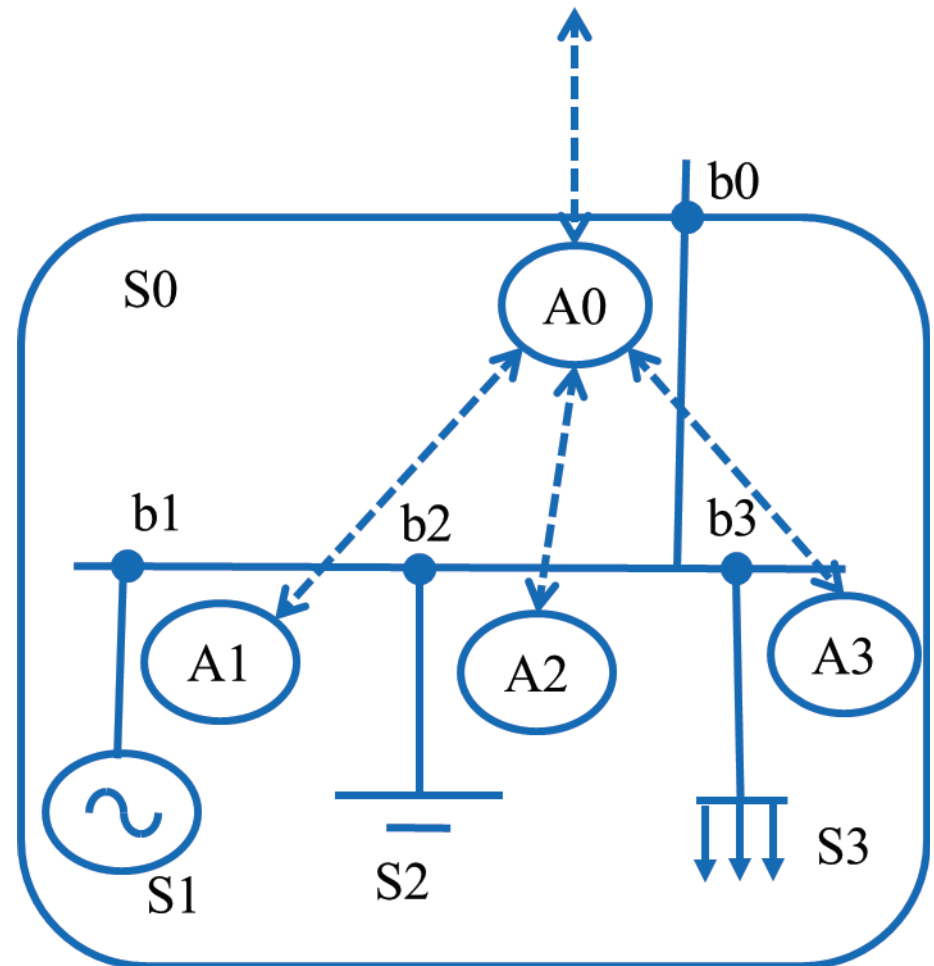
Optimal and robust control of bulk systems with high-volatile resources

1. Real time
2. Bug free
(i.e. simple)
3. Scalable
4. Composable
e.g. TN1 can control DN2; DN2 can control SS1



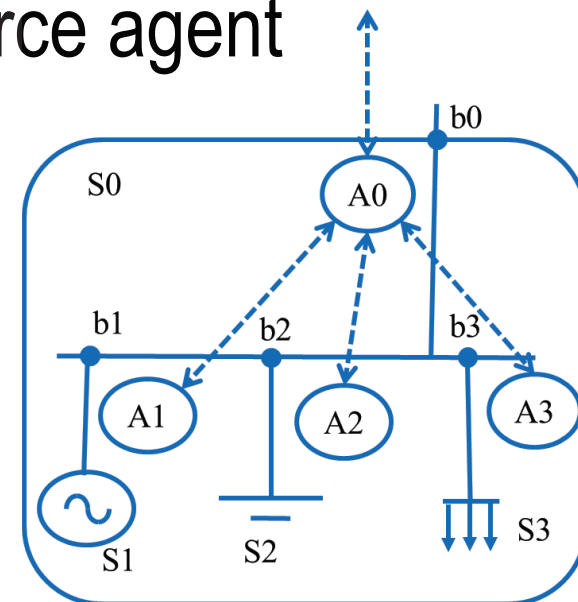
COMMELEC's Architecture

- **Software Agents**
associated with devices
 - load, generators, storage
 - grids
- **Grid agent sends explicit *power setpoints* to devices' agents**

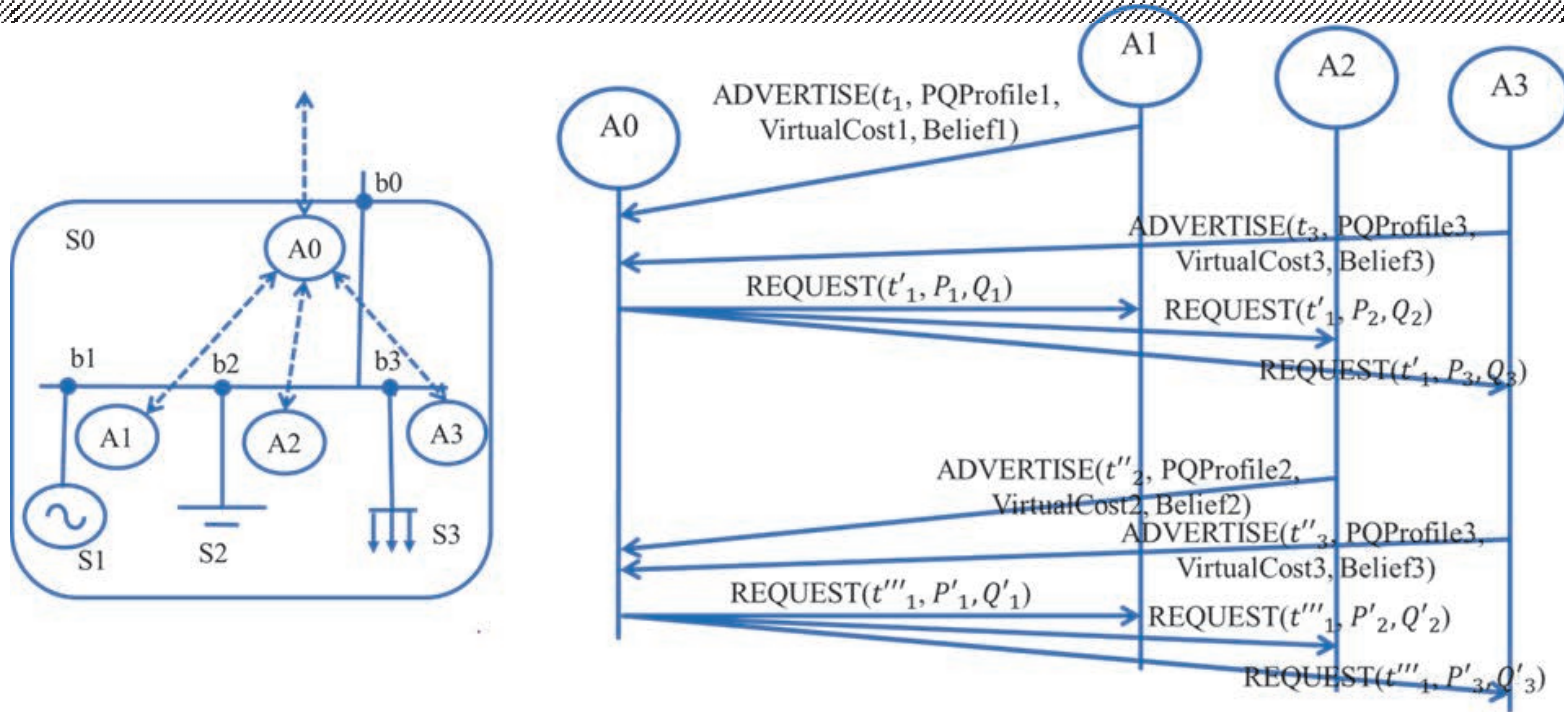


COMMELEC's Architecture – Resources and Agents

- Resources can be
 - controllable (sync generator, battery)
 - partially controllable (PVs, boilers, HVAC, TCLs)
 - uncontrollable (load)
- Each resource is assigned to a resource agent
- Each grid is assigned to a grid agent
- Leader and follower
 - resource agent is follower or grid agent
 - LV grid agent is follower of MV agent



COMMELEC's Architecture – The Protocol

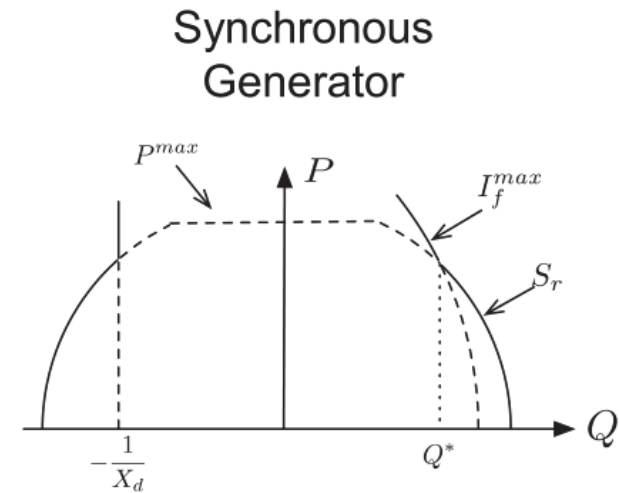
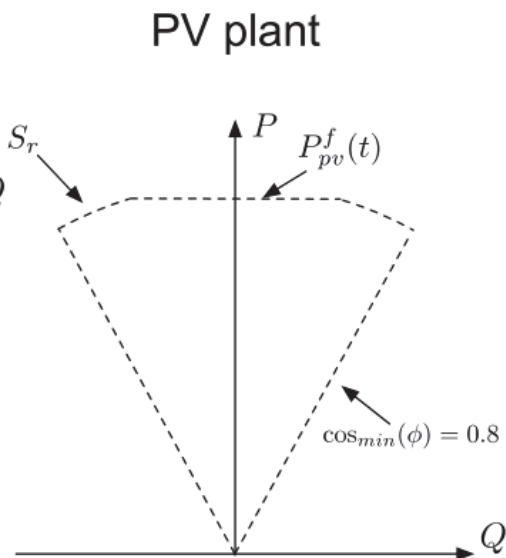
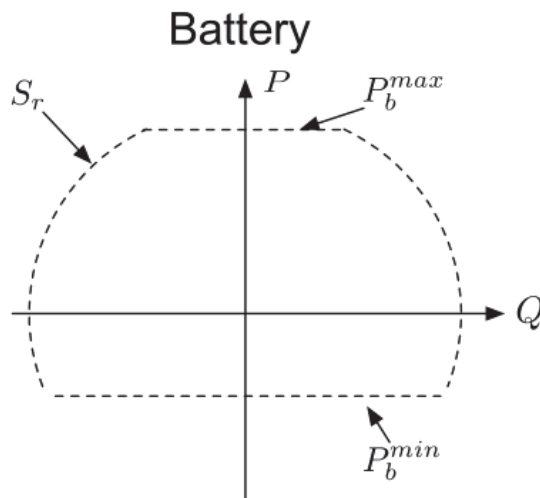


- Every agent advertises its state (example each 100 ms) as a *PQt profile*, a *virtual cost* and a *belief function*
- Each Grid agent computes optimal setpoints and sends them as requests to resource agents.

COMMELEC's Architecture – The PQt Profile

PQt profile as a system of coordinates for any resource connected to the grid.

Examples of *PQt* profiles



COMMELEC's Architecture – The Virtual Cost

Virtual cost acting as proxy for the resource internal constraints

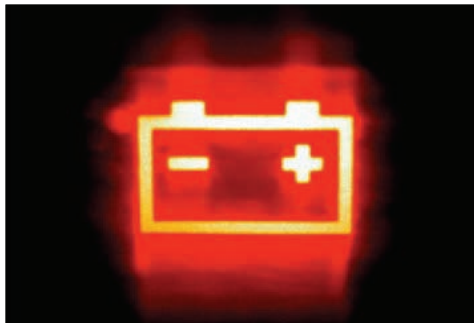
I can do P, Q in the next t
It cost you (virtually) $C(P, Q)$

Example:

If (State-of-Charge) is 0.7
I am willing to inject power

If (State-of-Charge) is 0.3,
I am interested in absorbing power

Battery agent

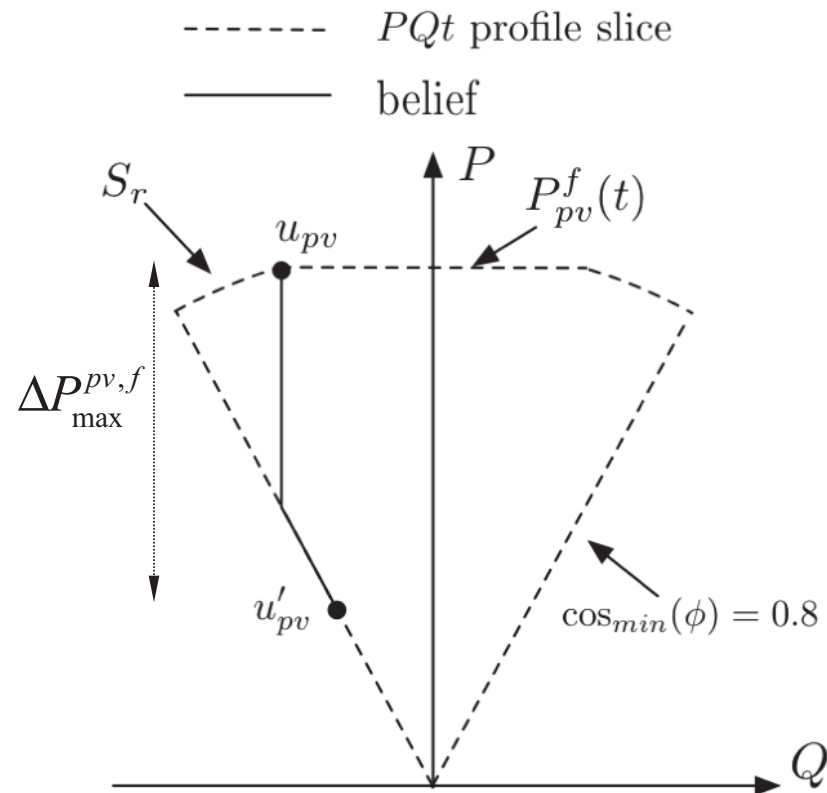


Grid agent



COMMELEC's Architecture – The Belief Function

- Say grid agent requests setpoint (P_{set}, Q_{set}) from a resource
- Actual setpoint (P, Q) **will, in general, differ**
- The **belief function** is exported by a resource agent with the semantic: resource implements $(P, Q) \in BF(P_{set}, Q_{set})$
- It gives bounds on the actual (P, Q) that will be observed when the follower is instructed to implement a given setpoint.
- Essential for safe operation.



COMMELEC's Architecture – The Grid Agent's Job

- **Leader agent (grid agent)** computes setpoints for followers based on
 - the state of the grid
 - advertisements received from the resources
- The Grid Agent attempts to minimize

$$J(x) = \sum_i C(x_i) + W(z)$$

Virtual cost of the resources

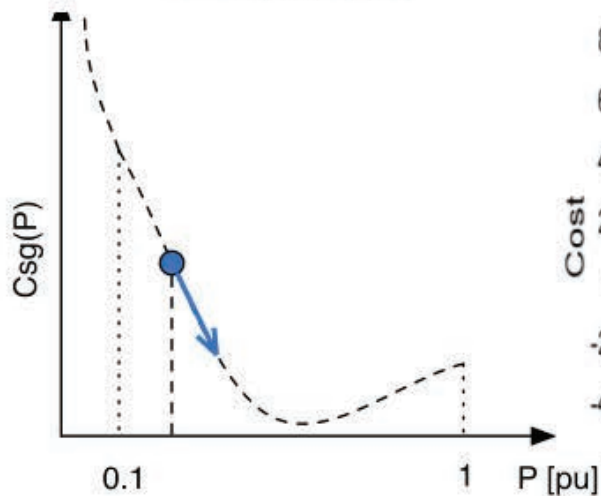
Penalty function of grid electrical state z (e.g., voltages close to 1 p.u., line currents below the ampacity)

- The Grid Agent **does not see the details of resources**
 - a grid is a collection of devices that export PQ_t profiles, virtual costs and belief functions and has some penalty function
 - problem solved by grid agent **is always the same**

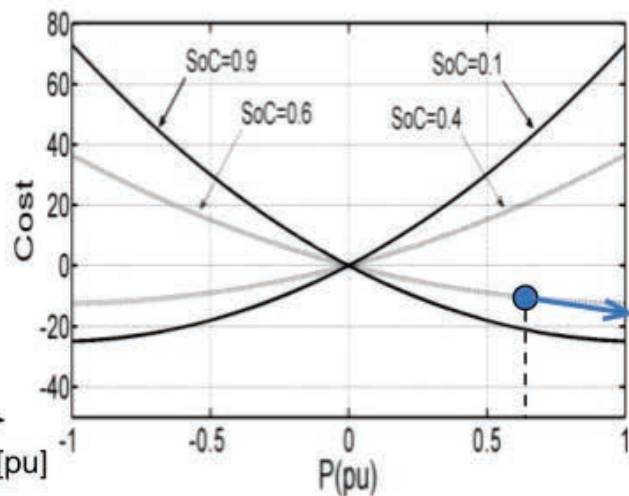
COMMELEC's Architecture – The Grid Agent's Job

Setpoint Computation by Grid Agent involves gradient of overall objective = sum of virtual costs + penalty

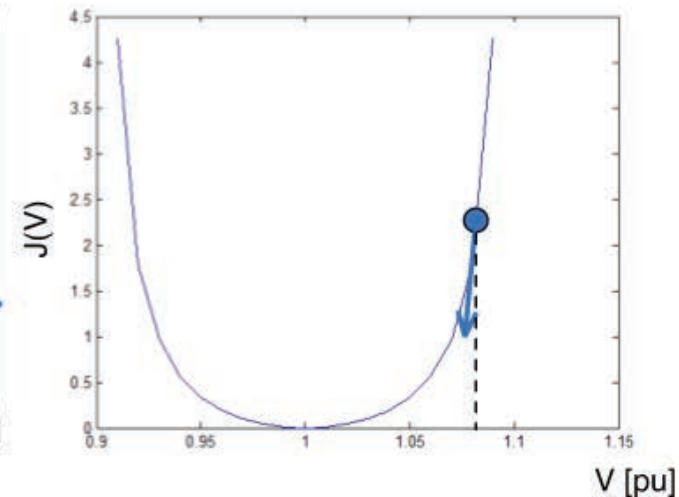
Synchronous Generator



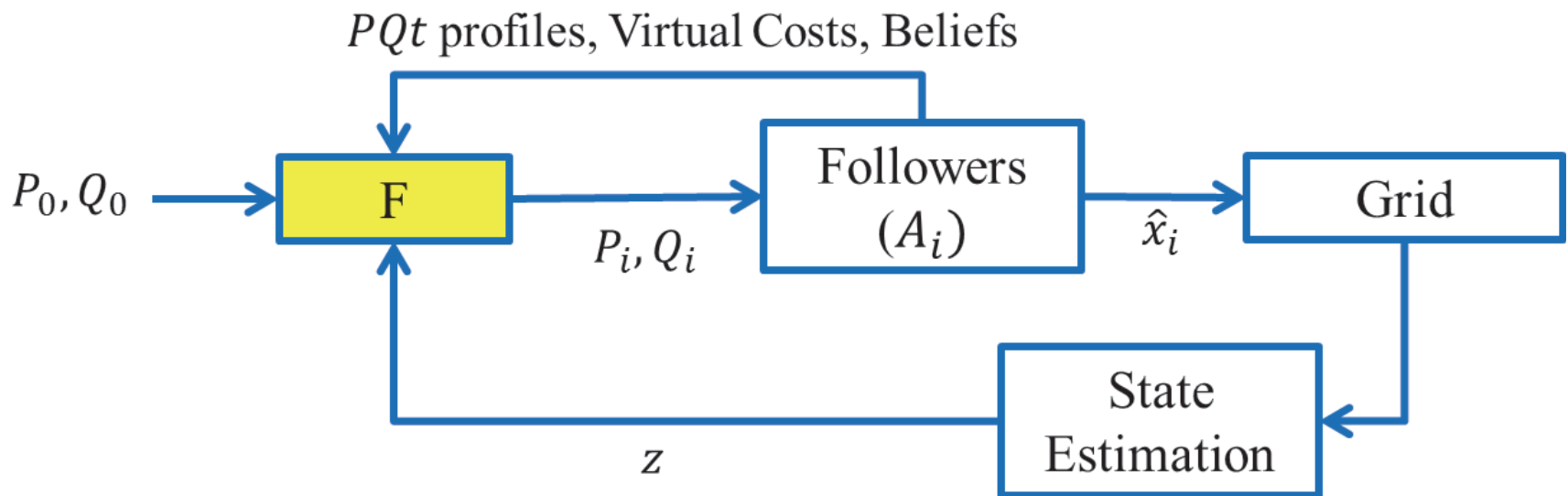
Battery



Voltage deviation penalty



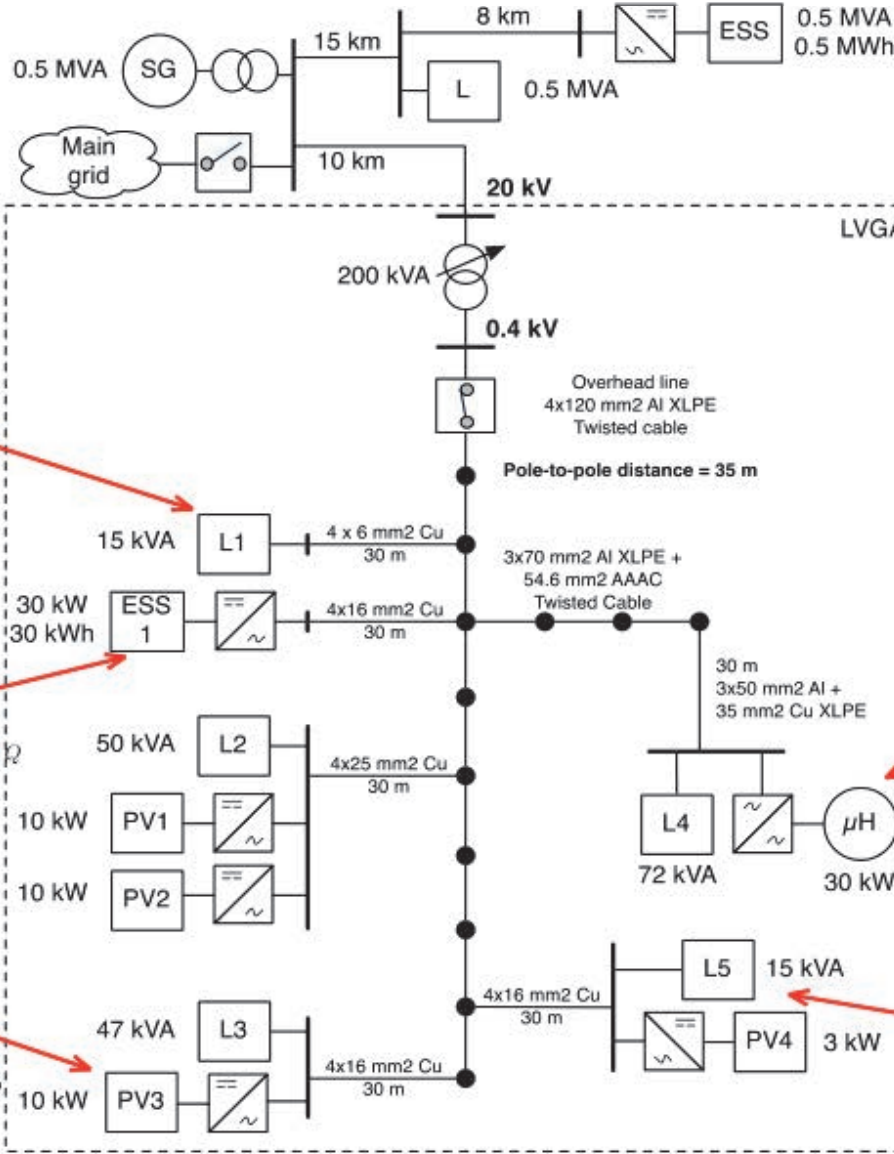
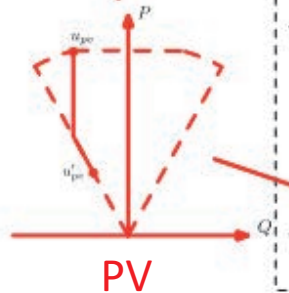
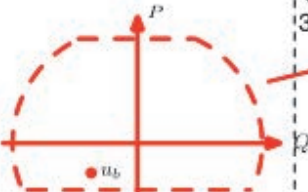
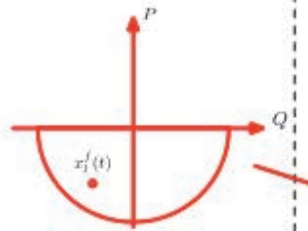
COMMELEC's Architecture – The Grid Agent's Job



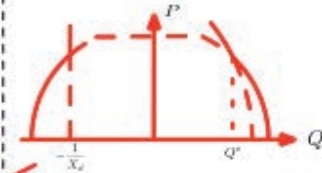
COMMELEC's Architecture – Aggregation, Composability

non controlled load

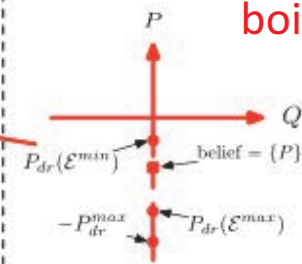
battery



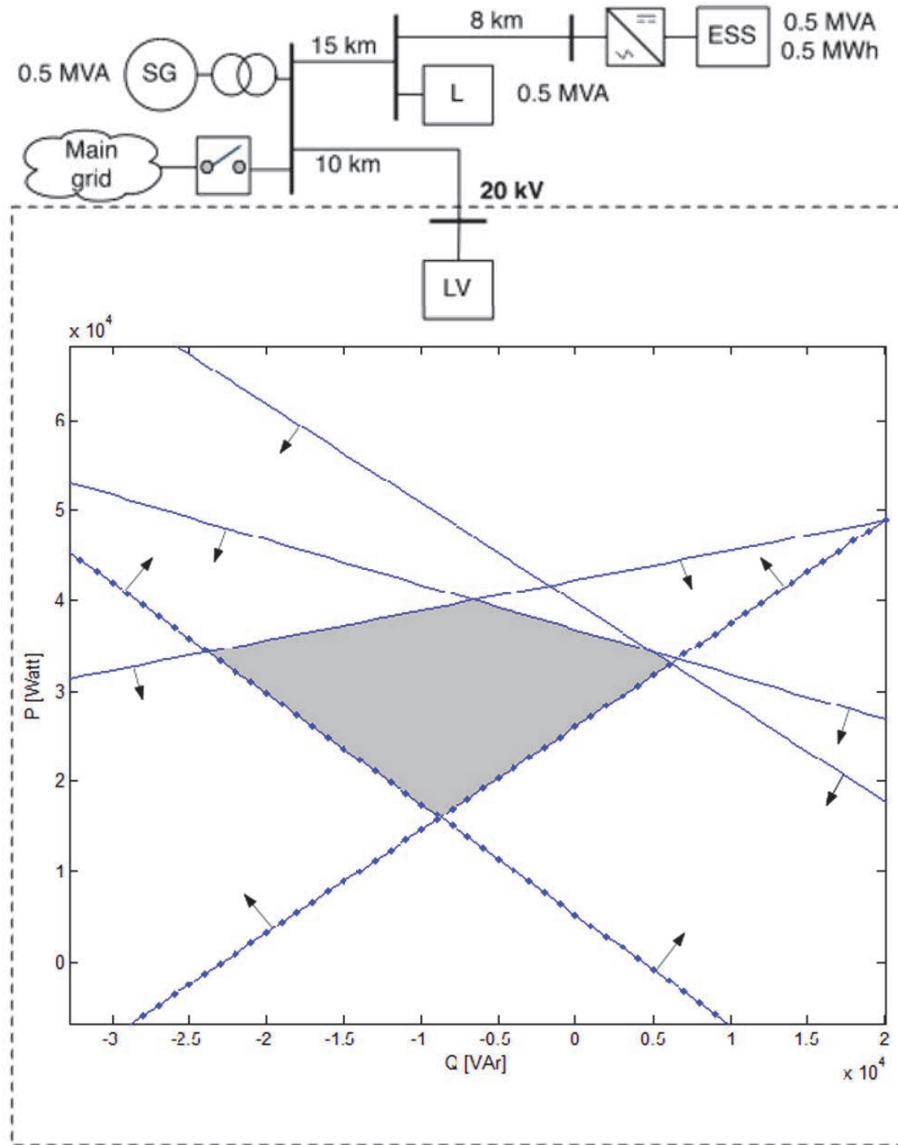
microhydro



boiler



COMMELEC's Architecture – Aggregation, Composability



Aggregated PQ_t profile

safe approximation
(subset of true aggregated PQ_t profile)

COMMELEC's Architecture – The Grid Agent's Job

- **Observe** and **estimate the state** of the grid;
- Compute the **safe state of the grid**
- Compute **optimal setpoints** to be forwarded to the **resource agents** to steer the electrical state of the grid to:
 - Minimize the cost of the followers
 - Satisfy the leader's request as much as possible
 - Maintain the grid in a safe state of operation

COMMELEC's Architecture – The Grid Agent's Job

Observe and estimate the state of the grid;

